

## Proposal for the 2016 ANES Time Series

### Quantitative Predictions of State and National Election Outcomes

**Keywords:** Election predictions, motivated reasoning, natural experiments, citizen competence, measurement

Can ordinary citizens predict election outcomes? This question is of growing importance in political science for several reasons. First, given declining response rates and increased use of mobile phones, scholars are increasingly looking to crowd-sourced predictions as a supplement for more traditional forecasting methods (Zukin 2015; Graefe 2014). Second, expectations of election outcomes have been used to gain insight into partisan motivated reasoning (Thibodeau et al. 2015; Daniller et al. 2013; Enos and Hersh 2015). Third, given the increasing use of elections as “natural experiments,” it is important to gauge how unexpected these outcomes truly are through the use of pre-election forecasts (Snowberg et al. 2007; Gerber and Huber 2010; Caughey and Sekhon 2011).

Despite the importance of measuring citizen election predictions, traditional measures – such as those included on the ANES surveys since the 1950s – have been shown to be suboptimal for answering research questions about prediction, motivated reasoning, and the effects of elections. In recent work, Quek and Sances (2015) compare a “qualitative” measure of election forecasts – who citizens think will win the election – to a “quantitative” measure – the vote share that citizens believe each candidate will receive. Building on work by Ansolabehere et al. (2013), Quek and Sances argue that asking about vote shares yields a more precise measure of the theoretical quantity of interest. They then show that, as expected, the vote share measure performs better in numerous empirical applications.

We propose that the 2016 ANES Time Series include the quantitative measure of election predictions used by Quek and Sances (2015) in their study of the 2012 U.S. presidential election. The original question used by these scholars asks about vote share in the national election. As an extension of the original study, we also propose to ask a question about expected vote shares of candidates in respondent’s state and county. **We therefore request a total of three survey items,**

detailed below.

Adding these quantitative prediction measures will enhance the ability of ANES data to answer research questions about prediction, motivated reasoning, partisan bias in economic expectations, and the effect of electoral closeness on turnout. Additionally, the presence of these items on the ANES, which also includes measures of media consumption and social networks, will allow us to better assess the determinants of election predictions. Several existing studies have shown that ordinary voters are surprisingly accurate when it comes to predicting elections, and including these items on the ANES can help to explain the causes of this accuracy.

## **Measurement**

### *Existing ANES Items*

Since 1952 and including in the 2012 Time Series Study,<sup>1</sup> the ANES has asked the following two items:

*Who do you think will be elected President in November?*

*<Democratic Candidate Name>*

*<Republican Candidate Name>*

*What about here in <state>? Which candidate for President do you think will carry this state?*

*<Democratic Candidate Name>*

*<Republican Candidate Name>*

While these measures have yielded a powerful time series of election predictions that has already been employed by researchers (e.g., Rothschild and Wolfers 2013; Graefe 2014), they are limited

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<sup>1</sup>Response options may have changed slightly over the years. We refer to the wordings from the 2012 Time Series in this proposal.

in that they only ask respondents about *who will win*, and not by how much. In the framework of Ansolabehere et al. (2013), the existing measure is a “qualitative” measure of a “quantitative” theoretical construct. Existing work on election predictions highlights the problems this causes. For instance, to translate the responses to vote shares, researchers must impose additional functional form assumptions to make the binary response continuous (Lewis-Beck and Tien 1999). Similarly, some scholars have sought to use “over-confidence” in election predictions as evidence of partisan motivated reasoning (Thibodeau et al. 2015; Daniller et al. 2013). Yet the binary prediction measure is difficult to interpret in this regard: 90% of Republicans may believe their candidate will win, but their over-confidence would be better measured if we knew *by how much* they think their candidate would win.

*Proposed Items for the 2016 Time Series*

In recent work, Quek and Sances (2015) report the results of an online survey fielded in the 2012 presidential election and administered by the firm Survey Sampling International. On this survey, Quek and Sances asked not only about expectations of who would win, but also about expectations of vote share. We propose to include the following variants of this question on the 2016 survey:

*1. Thinking about only the votes cast for the two major parties, what percentage of the vote do you think <Democratic Candidate Name> and <Republican Candidate Name> will each receive in the NATIONAL VOTE?*

*<Democratic Candidate Name> \_\_\_\_\_ %*

*<Republican Candidate Name> \_\_\_\_\_ %*

*2. Thinking about only the votes cast for the two major parties, what percentage of the vote do you think <Democratic Candidate Name> and <Republican Candidate Name> will each receive in YOUR STATE?*

*<Democratic Candidate Name> \_\_\_\_\_ %*

*<Republican Candidate Name> \_\_\_\_\_ %*

*3. Thinking about only the votes cast for the two major parties, what percentage of the vote do you think <Democratic Candidate Name> and <Republican Candidate Name> will each receive in YOUR COUNTY?*

*<Democratic Candidate Name> \_\_\_\_\_ %*

*<Republican Candidate Name> \_\_\_\_\_ %*

As in the 2012 study, respondents options will be constrained to sum to 100.

#### *Validation of Proposed Measures*

In this section we present evidence for the validity of the vote share prediction measure from Quek and Sances (2015). The data come from an online sample of about 2,700 U.S. respondents in October 2012. Figure 1 below shows the distribution of vote share predictions, first for the entire sample and then by partisan subgroup. This figure shows that among the full sample, predictions are approximately normally distributed around the actual vote share result of 51.9% for Barack Obama. On average, respondents were off by only about one percentage point. The remaining panels of the figure show that prediction bias was lowest among independents (1.5 points overestimating for Obama), six points over for Democrats, and five points under for Republicans. (By way of comparison, expert forecasts published in the October 2012 issue of PS: Political Science and Politics had an average error of 1.7% (Campbell 2012), and the October 31, 2012, Iowa Electronic Market had an error of 1.4%.)

Figure 1:

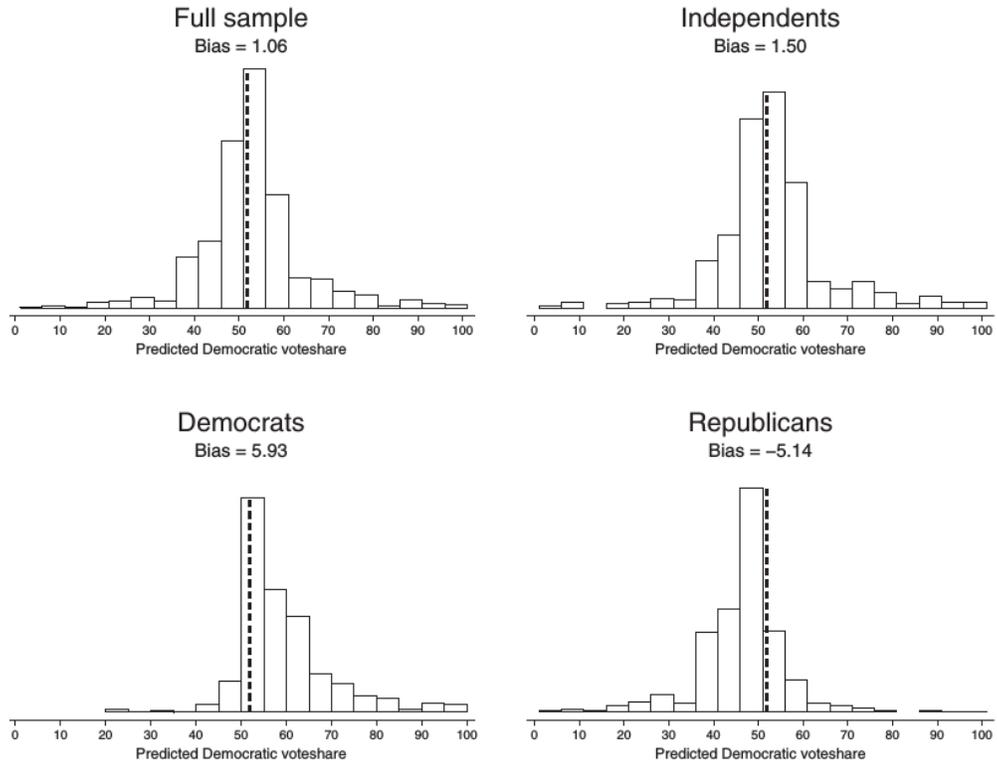
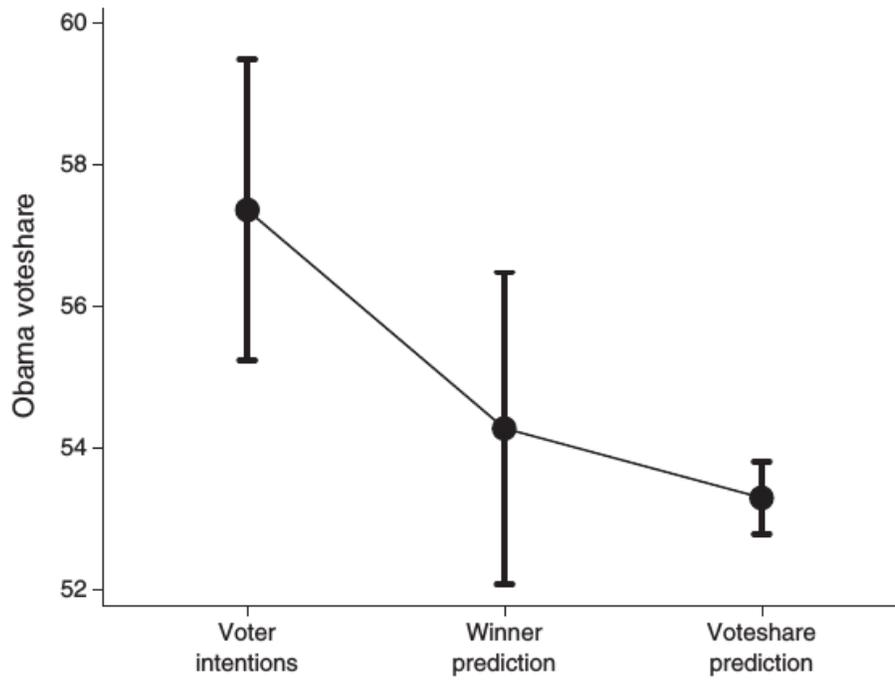


Figure 2:



Quek and Sances (2015) also show that the vote share prediction performs better than alternative measures. Figure 2 below compares the average Obama vote share obtained using three questions: who respondents intended to vote for; who respondents predicted would win; and our vote share prediction question. This figure shows that while the binary prediction measure yields more accurate forecasts than the intention measure, the vote share measure is both more accurate, as well as more precise, as evidenced in the tighter confidence interval.

The vote share measure not only performs better in terms of forecasting elections, but is also better suited as a measurement of “electoral surprise.” In a study of the effect of partisanship on economic perceptions, Gerber and Huber (2010) show that election outcomes change how Republicans and Democrats evaluate the future economy: if a voter’s favored candidate wins (loses), then that voter expects the economy to do better (worse) in the future. Quek and Sances (2015) show that prediction measures can be used to enhance this effect. They compare how economic perceptions change before and after the 2012 election between Democrats and Republicans, as well as how the partisan differential changes as a function of electoral expectations. As shown in Table 1 below, while Republicans became more negative about the economy after the election (columns 1 and 2), this effect was higher for Republicans who were “surprised” – that is, who believed Obama would lose (columns 3 and 4). The interaction effects indicate that the most surprised Republicans shifted about 0.6 (on a five-point scale) more in economic expectations than the least surprised. Yet the final two columns show that the vote share prediction measure brings this effect into sharper relief: the interactions are over three times as high (all predictors are coded such that zero (one) is the sample minimum (maximum)).

### **Justification for Proposed Items**

Based on the results in Quek and Sances (2015), we believe the inclusion of the national vote share prediction (question 1 above) is warranted given the widespread use of election predictions to answer numerous research questions, and the demonstrated superiority of the vote share measure as compared to the traditional binary measure. Further, including the vote share measure only adds

Table 1:

	<i>Baseline</i>		<i>X winner prediction</i>		<i>X voteshare prediction</i>	
	<i>(1)</i>	<i>(2)</i>	<i>(3)</i>	<i>(4)</i>	<i>(5)</i>	<i>(6)</i>
Republican	-0.72 (0.05)	-0.69 (0.05)	-0.85 (0.09)	-0.80 (0.09)	-1.53 (0.30)	-1.59 (0.30)
Prediction			-0.03 (0.08)	-0.01 (0.08)	0.35 (0.31)	0.18 (0.33)
Rep X prediction			0.57 (0.12)	0.56 (0.12)	1.84 (0.58)	1.99 (0.58)
Political knowledge		-0.20 (0.09)		-0.18 (0.08)		-0.19 (0.09)
Some college		0.06 (0.07)		0.04 (0.07)		0.06 (0.07)
Bachelors		0.05 (0.07)		0.04 (0.07)		0.05 (0.07)
Postgraduate		0.25 (0.07)		0.24 (0.07)		0.24 (0.07)
Income		-0.02 (0.01)		-0.03 (0.01)		-0.02 (0.01)
Turnout		-0.03 (0.08)		-0.02 (0.07)		-0.02 (0.08)
Age		-0.00 (0.00)		-0.00 (0.00)		-0.00 (0.00)
Female		-0.01 (0.05)		-0.00 (0.05)		-0.00 (0.05)
Black		0.01 (0.08)		0.01 (0.08)		0.01 (0.09)
Other race		0.03 (0.10)		0.03 (0.10)		0.02 (0.09)
Constant	0.01 (0.03)	0.45 (0.14)	0.04 (0.07)	0.44 (0.15)	-0.19 (0.18)	0.32 (0.22)
Observations	1175	1175	1175	1175	1175	1175

*Note.* Standard errors in parentheses.

additional information, and does not lose any information: researchers who are interested in who respondents thought would win can easily transform the vote share measure into a binary measure. However, the reverse is not possible.

In addition to the national vote share prediction, we are requesting questions that ask about respondents' expected vote share in their state (question 2) and county (question 3). We have several reasons for adding these items. First, the ANES has paired its traditional national election prediction measure with a question asking about who respondents believe will win in their state. While existing research has compared the binary and continuous measures using predictions of

national elections, no study has made this comparison at the state level.

Second, asking about predictions at more refined levels of geography will help researchers address an open question: just why do respondents do so well at predicting elections (Rothschild and Wolfers 2013; Quek and Sances 2015). One explanation, proposed by Rothschild and Wolfers, is that respondents pool information from their immediate social networks when answering prediction questions. While plausible, this explanation has yet to be tested; indeed, an equally plausible – but also untested – explanation is that respondents form their predictions as a weighted average of their own vote intent and what they have heard about polls in the media. If respondents are better at predicting state and county outcomes – levels of geography where respondents know more people personally, but where polls are less likely to be publicized – then this is informative about the causes for accuracy in election predictions.

Third, asking about vote share predictions at lower levels of geography is informative for studying the effect of “perceived pivotality” on turnout (Aldrich 1976; Enos and Fowler 2014). According to the calculus of voting (Riker and Ordeshook 1968), turnout should be increasing in the perceived closeness of the outcome. While the ANES has in the past asked about perceived closeness, they have done so using a qualitative measure with just two response options.<sup>2</sup> By employing a quantitative measure of closeness, researchers will be better able to evaluate whether perceptions of electoral closeness matter for voter turnout.

Finally, the longitudinal nature of the ANES Time Series will allow researchers to test how respondents adjust their expectations in response to campaign events – and, in turn, how shifting expectations regarding candidate viability affect vote choice.

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<sup>2</sup>For instance, in the 2012 Time Series, the item was worded “Do you think the Presidential race will be CLOSE here in <state> or will one candidate win by quite a bit?” The response options were “Will be close” or “Win by quite a bit.”

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